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BTECH
(SEM VII) THEORY EXAMINATION 2024-25
DEEP LEARNING

TIME: 3 HRS

M.MARKS: 100

Note: Attempt all Sections. In case of any missing data; choose suitably.

SECTION A

1. Attempt all questions in brief. 2 x 10 = 20

Q no.	Question	CO	Level
a.	Discuss the differences between a perceptron and a support vector machine in terms of decision boundary formation.	1	K ₁ , K ₂
b.	Discuss how the choice of a loss function affects model performance for a classification problem.	1	K ₁ , K ₂
c.	Trace the historical development of deep learning that enabled deep networks to outperform traditional machine learning models.	2	K ₁ , K ₂
d.	How does weight sharing in CNNs improve efficiency and performance?	2	K ₁ , K ₂
e.	Explain the impact of weight initialization on the performance of deep networks.	3	K ₂
f.	Compare performance of autoencoders with traditional dimensionality reduction techniques.	3	K ₂
g.	Provide examples of optimization algorithms used for deep networks.	4	K ₂ , K ₃
h.	How do techniques address the challenges of stochastic optimization in deep learning?	4	K ₂ , K ₃
i.	Describe the architecture and training of WaveNet for audio generation.	5	K ₃ , K ₆
j.	Discuss the role of Word2Vec in natural language processing.	5	K ₃ , K ₆

SECTION B

2. Attempt any three of the following: 10 x 3 = 30

a.	Derive the gradient of the logistic regression loss function with respect to its parameters. How does regularization impact its optimization process?	1	K ₁ , K ₂
b.	Define VC dimension and discuss its implications for understanding the generalization capabilities of deep networks.	2	K ₁ , K ₂
c.	Explain the role of manifold learning in dimensionality reduction. How does it compare to linear methods?	3	K ₂
d.	Explain the concept of generalization in neural networks. How do techniques like dropout and weight regularization improve generalization performance?	4	K ₂ , K ₃
e.	Discuss the pipeline of scene understanding using deep learning models. How does this pipeline handle challenges like occlusion and varying lighting conditions?	5	K ₃ , K ₆

SECTION C

3. Attempt any one part of the following: 10 x 1 = 10

a.	Prove that neural networks can act as universal function approximators. Discuss any constraints or assumptions involved in this theorem.	1	K ₁ , K ₂
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b.	Discuss the relationship between the choice of activation function in a shallow neural network and its ability to model non-linear relationships.	1	K ₁ , K ₂
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4. Attempt any one part of the following: 10 x 1 = 10

a.	Analyze the trade-offs between increasing network depth and the risk of vanishing/exploding gradients. What role does skip connections in ResNet play in addressing these issues?	2	K ₁ , K ₂
b.	How does semi-supervised learning differ from supervised and unsupervised learning? Discuss its application in training deep networks with limited labeled data.	2	K ₁ , K ₂

5. Attempt any one part of the following: 10 x 1 = 10

a.	Explain the concept of metric learning in the context of dimensionality reduction. How does it differ from traditional techniques like PCA	3	K ₂
b.	Analyze the architectural differences between AlexNet, VGG, Inception, and ResNet. How do these architectures address the vanishing gradient problem?	3	K ₂

6. Attempt any one part of the following: 10 x 1 = 10

a.	Discuss the implications of non-convex optimization in designing deep learning models. How do saddle points influence the training process?	4	K ₂ , K ₃
b.	Provide a detailed overview of computational neuroscience principles applied in designing artificial neural networks.	4	K ₂ , K ₃

7. Attempt any one part of the following: 10 x 1 = 10

a.	Provide a detailed overview of deep learning-based techniques for audio detection. How does WaveNet outperform traditional methods?	5	K ₃ , K ₆
b.	Describe the process of joint detection and captioning in image captioning systems. How does attention enhance this process?	5	K ₃ , K ₆